



RFID Performance Characteristics

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About RFID Alliance Lab

- ◆ Provide useful, timely, credible, and unbiased data to end users of RFID products
- ◆ Constituents
 - ◆ University of Kansas / ITTC
 - ◆ Primary research contributor
 - ◆ RFID Journal
 - ◆ Initial funding, distributor, advertisement
 - ◆ Rush Tracking Systems
 - ◆ Initiator, subject expert, industry lesion
- ◆ Business model
 - ◆ Sell reports (~\$1,000 / report) to finance future reports
 - ◆ Exploring alternative revenue



Why us, why now?

- ◆ RFID Revolution is under way
- ◆ Need to separate facts from hype
 - ◆ What you read \neq what you get
 - ◆ E.g., “commercially available” used very liberally
 - ◆ Problems / issues not exposed, little or no data
- ◆ Team
 - ◆ University credibility, diligence, approach
 - ◆ Industry involvement focuses on relevant, pressing problems
 - ◆ RFID Journal as publication platform to disseminate results



Performance Metrics

- ◆ Performance, not conformance
- ◆ Orientation sensitivity
- ◆ Tags near metal, water
- ◆ Read distance
- ◆ Variance in performance
- ◆ Conveyors



First Report

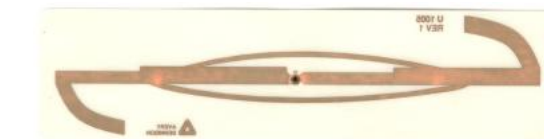
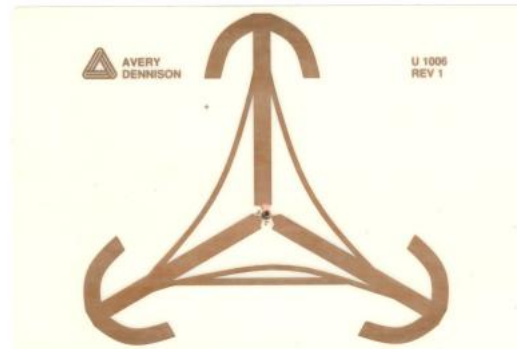
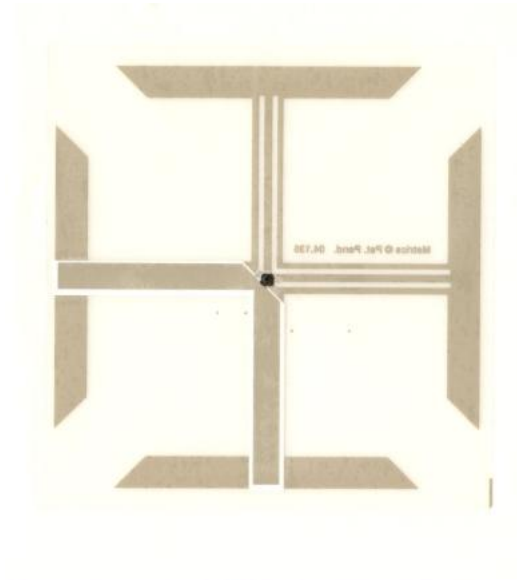
- ◆ Radiation Pattern (orientation sensitivity)
- ◆ Read Distance, typical
- ◆ Tags near metal
- ◆ Tags near water
- ◆ Conveyor testing



Tags Analyzed

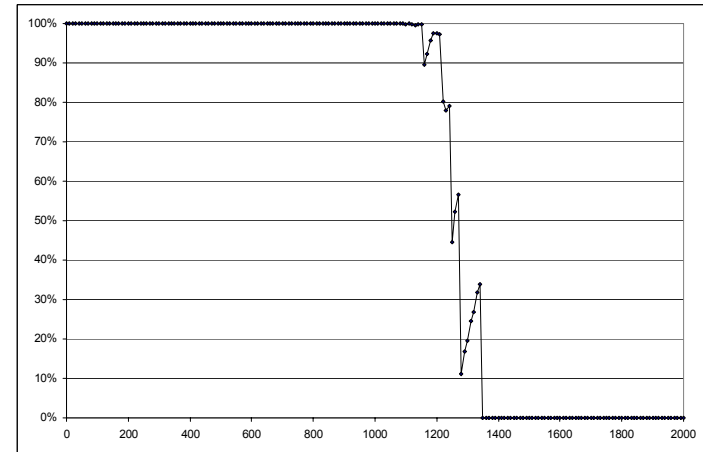
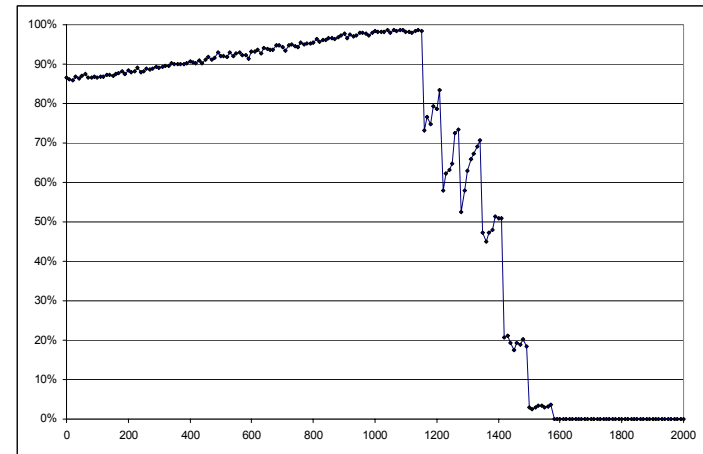
Tags:

- ◆ Matrics X2040
- ◆ Avery Triflex
- ◆ Rafsec 457
- ◆ Rafsec 458
- ◆ Alien 9250
- ◆ Alien 9338
- ◆ Alien 9254
- ◆ Avery U1014
- ◆ Matrics I2010
- ◆ Avery DS1



Typical Tag Performance vs. Distance

- ◆ How do you measure performance?
 - ◆ Successful reads / attempted reads
 - ◆ ThingMagic Mercury 4 reader
- ◆ 2 typical Class 1 tags
 - ◆ 5000 reads / power setting
 - ◆ 200 power settings





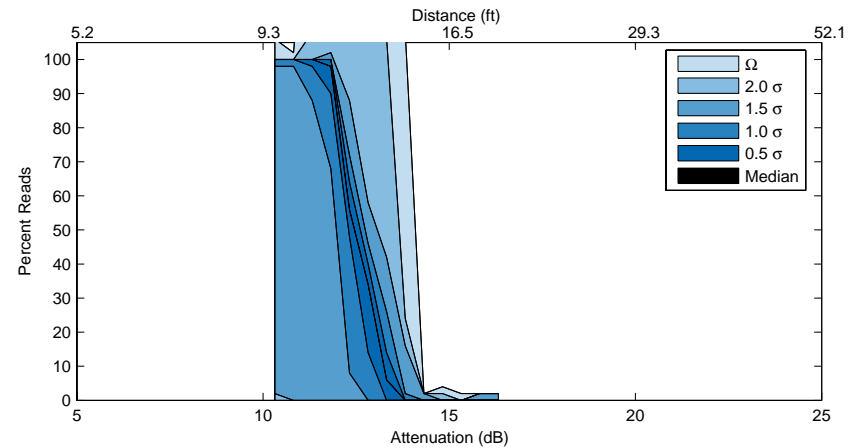
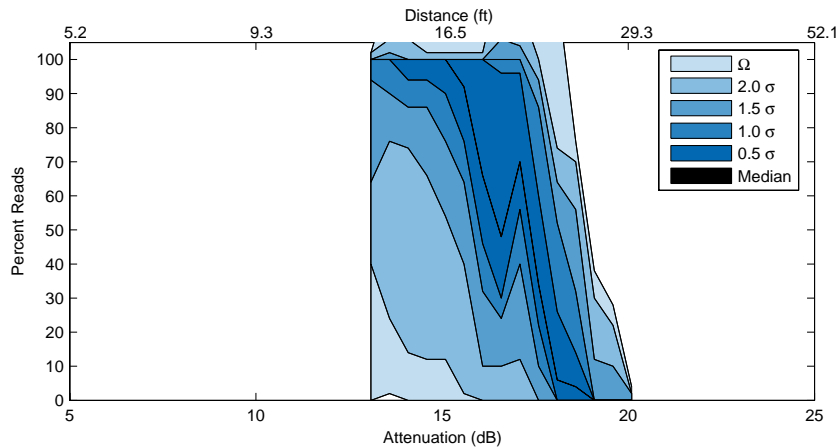
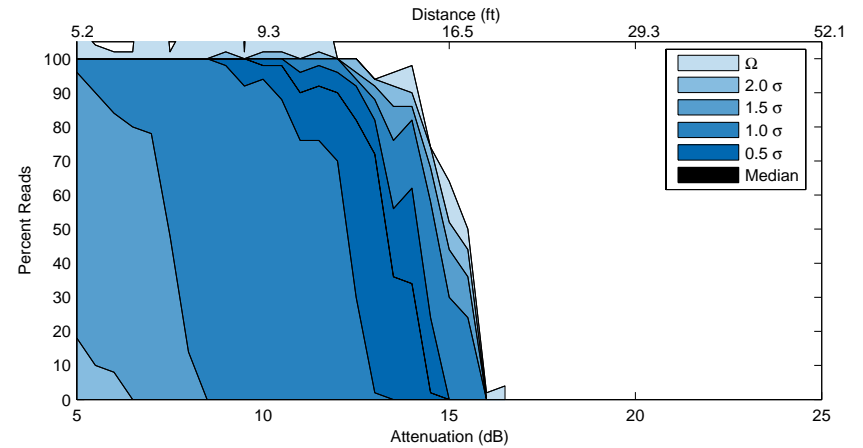
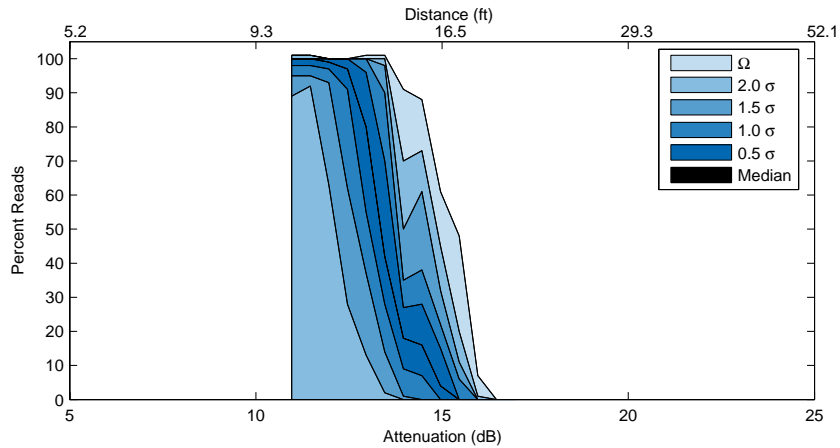
Variation of Tag Performance

- ◆ Tags vary in performance
 - ◆ Model to model
 - ◆ Tag to tag
- ◆ Experiment: Characterize performance of 100 tags of each model and compare.
- ◆ Within a tag model, classify tags by:

median	$.5\sigma$	σ	1.5σ	σ^2	Ω
black	dark blue	.	.	.	lightest blue
50%	31-69%	16-84%	7-93%	2-98%	0-100%
1 tag	38%	68%	86%	96%	100%

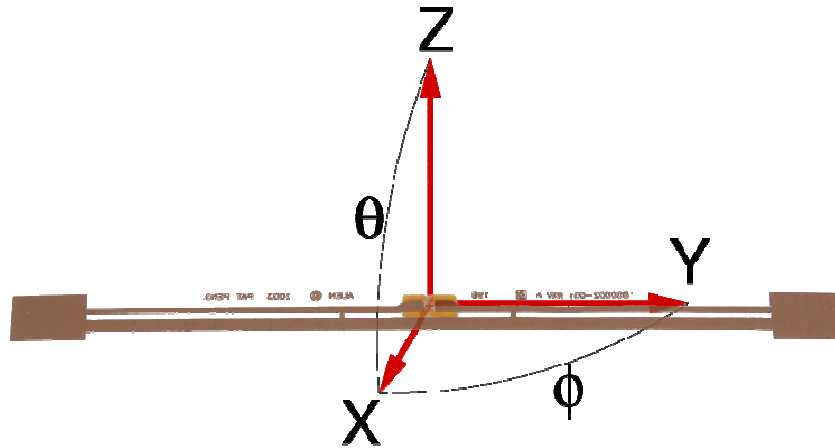


Four Tag Models (preliminary)





Angles and Axes



Rotation along the X-Y axes: φ

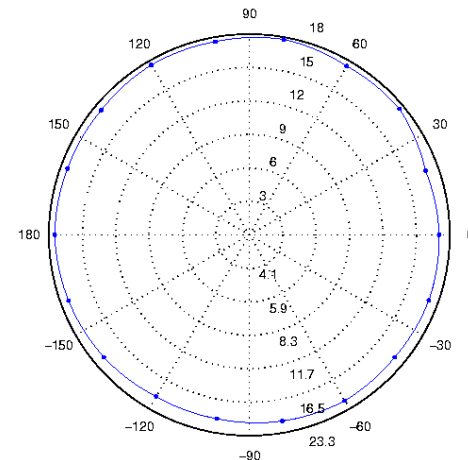
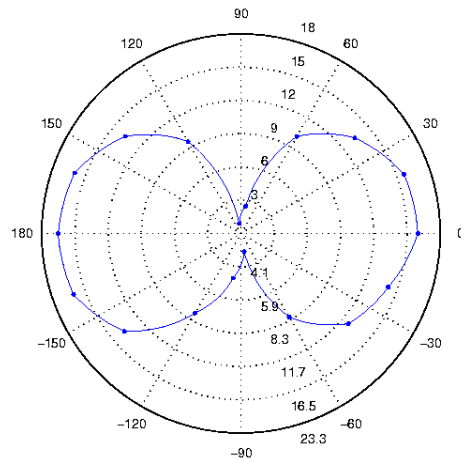
Rotation along the X-Z axes: θ

Rotation along the Y-Z axes: twisting

- ◆ Shouldn't matter with circularly polarized antennas, but our experience shows it does.



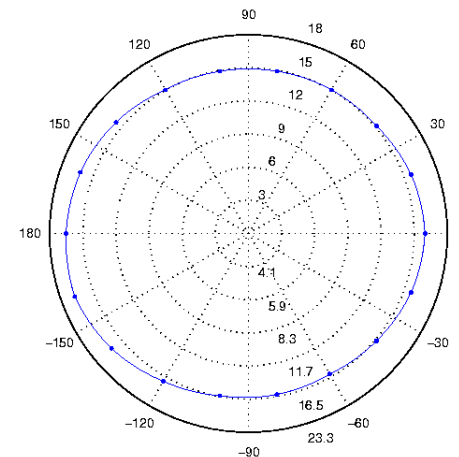
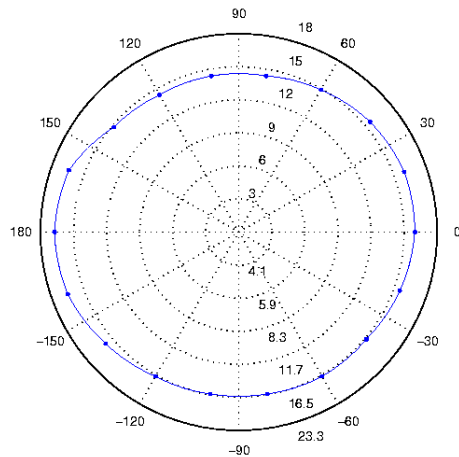
A “Dipole” Design



Characteristic of all long, narrow tags

- ◆ Read range nearly zero when looking at ends of dipole
- ◆ Read performance nearly uniform along other axis

A “Dual Dipole” Design

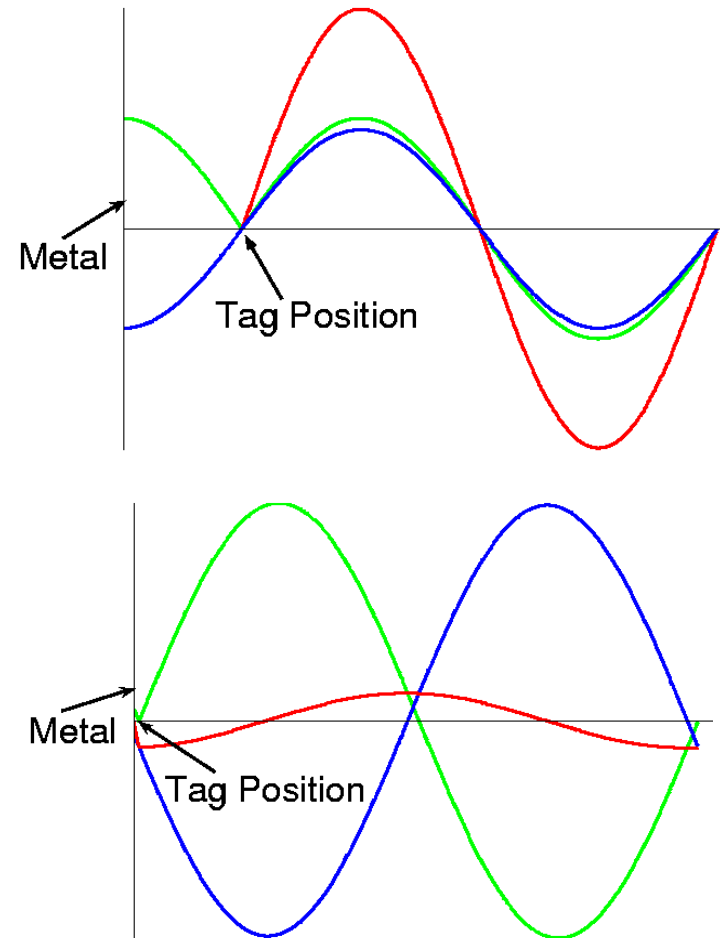


Characteristic of large, square/triangle

- ◆ Read performance nearly uniform in all orientations

Constructive/Destructive Interference

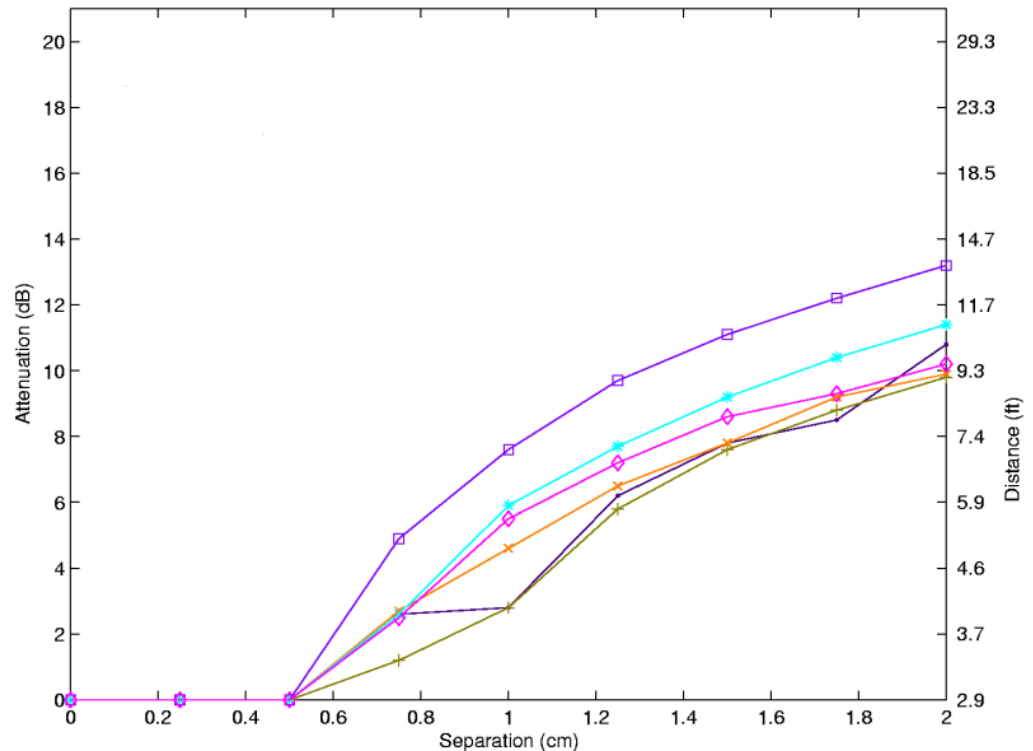
- ◆ Metal reflects RF 180 degrees out of phase
 - ◆ Can enhance RF signal (constructive)
 - ◆ Can degrade RF signal (destructive)
- ◆ Legend:
 - ◆ Green – transmitted
 - ◆ Blue – reflected
 - ◆ Red – superposition (received)





Performance of Class 1 Tags near Metal

- ◆ In destructive interference region
 - ◆ most difficult
- ◆ Best tag:
 - ◆ 150% more efficient than worst
 - ◆ 60% further distance

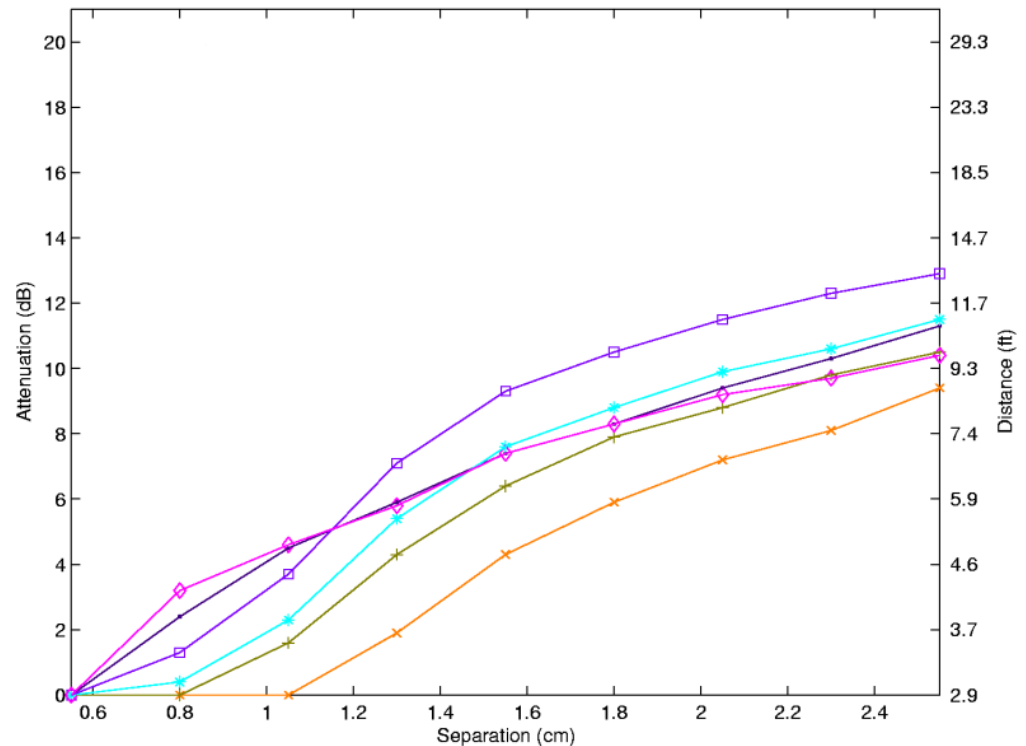




Performance of Class 1 Tags near Water

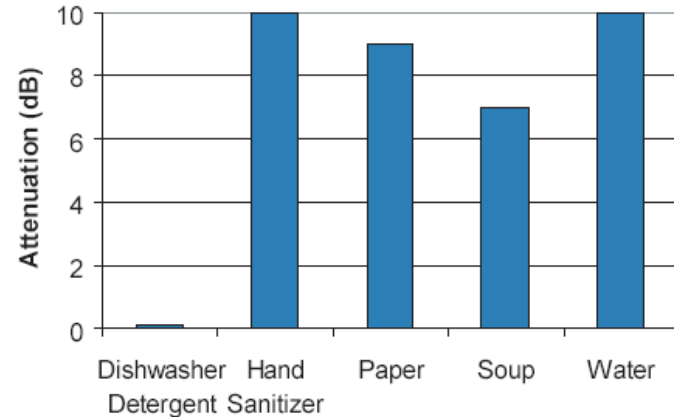
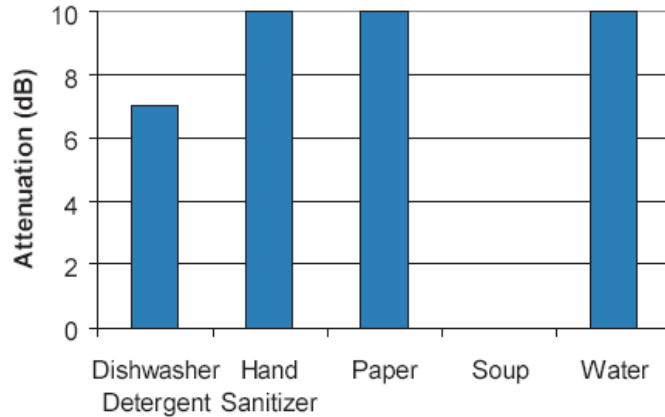
Differences readily apparent

- ◆ Pink best close, but shallow slope
- ◆ Purple good close, but best further
- ◆ Best tag:
 - ◆ 150% more efficient than worst
 - ◆ 60% further distance





Tags on Conveyor



- ◆ **Least scientific test conducted**
 - ◆ 2400 measurements taken
- ◆ **Interesting experiment — objective is to get as far away from metal/water as possible**
- ◆ **Size of tag plays large role**
 - ◆ Smaller tags get bigger air gaps



Summary from First Report

- ◆ Not all tags are created equal
- ◆ Consider neighboring materials
 - ◆ Metal and water can substantially degrade performance (get as far away as possible)
 - ◆ Interaction between packaging and tag can cause unexpected problems
- ◆ Be cautious not to over-generalize results



Future Projects

- ◆ Durability
 - ◆ ESD
 - ◆ Shock
- ◆ Open Pilot
- ◆ OpenRFID
 - ◆ Hardware and software platforms



How Can I Participate

- ◆ Buy a report
- ◆ Partnerships
 - ◆ Advisory roll
 - ◆ Special access
 - ◆ Perform testing on your site, involve your people
- ◆ Special projects
- ◆ Donations (money, equipment, time, etc.)



Conclusions

- ◆ RFID is tricky — no “cookbook” solutions
 - ◆ Information that we’re gathering is valuable, but only part of the puzzle
- ◆ Don’t believe the hype
- ◆ What you don’t know can hurt you